



Program Sponsoring Work

DARPA – Bio:Info:Micro Grant No. MDA972-00-1-0029

Program Manager

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Co-Principal Investigators

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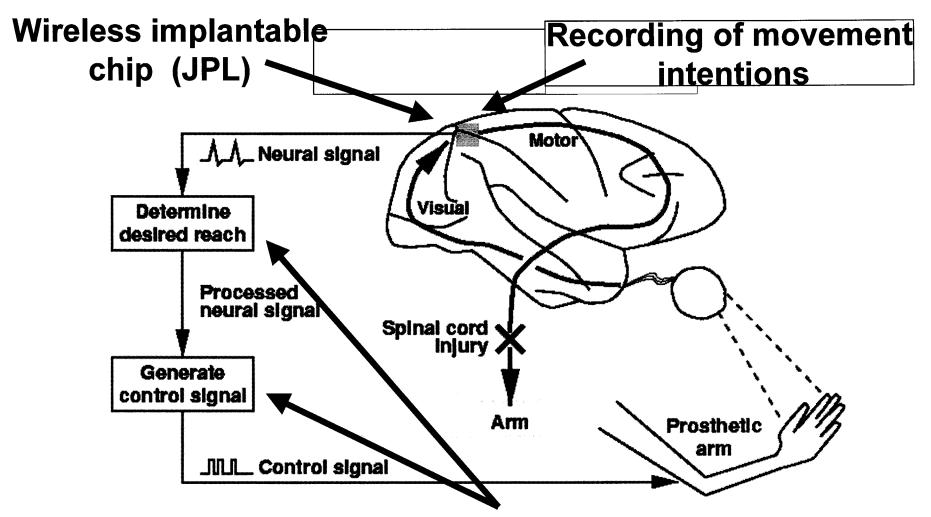
Affiliation

California Institute of Technology, Jet Propulsion Lab, Bell Labs



Using the posterior parietal cortex for a neural prosthesis ___





Readout for robotic control



Unique features of our research



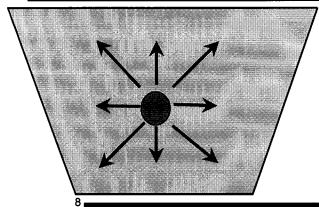
- 1) We use cognitive (planning) signals rather than motor (execution) signals. May be easier to generate plans and may require fewer neurons.
- 2) We record from visual-motor rather than somatic-motor areas.
 - a) This may be an advantage for providing sensory feedback for prosthetic control.
 - b) The visual-motor areas of the posterior parietal cortex are very plastic.
 - c) The visual motor areas may show less degeneration with paralysis.



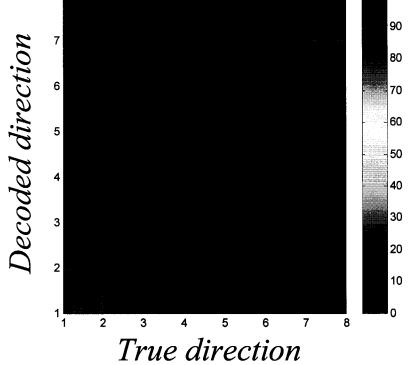
Decoding

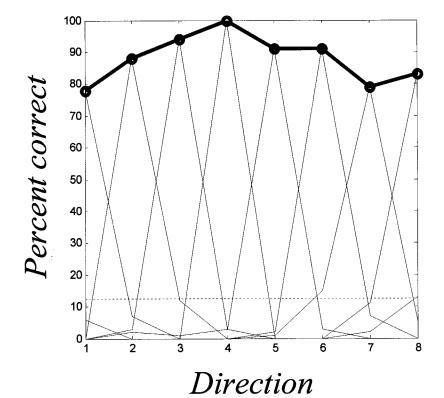
100





Decoding of 8 reach directions using 16 SPIKES



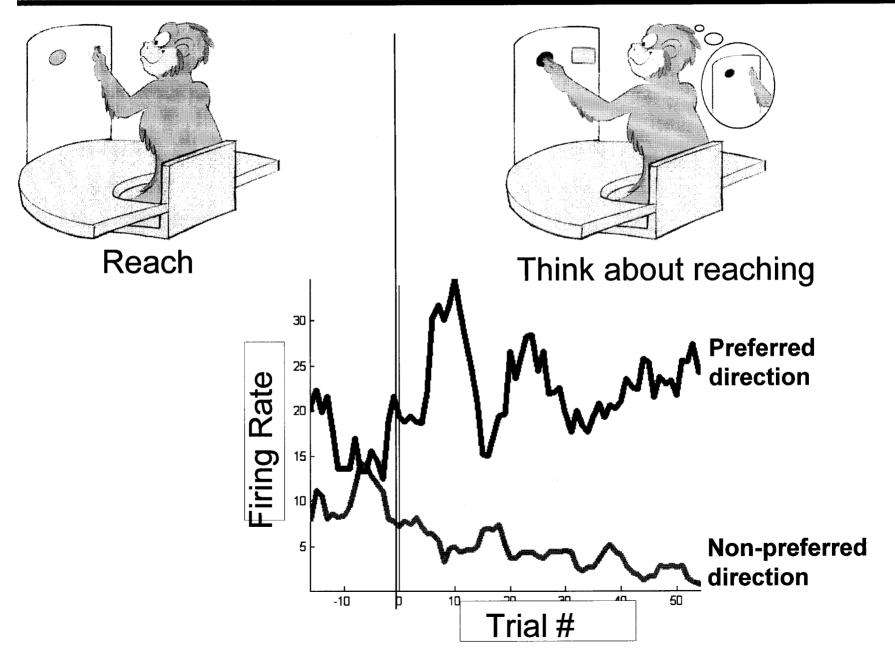


(n=16 recording sites)



Rapid Plasticity, Single Cell







System Diagram and Requirements

Analog Out

DB-9

Connec

PCMCIA

ADC Card

Serial Port

Frame

Detect

Clock

Voltad

RS-232

Driver/

Receiver



ASIC

Amplifiers

Mux Array

gain& latch

Logic

Shift Register

RAM

Command

Detect

PCB Test Fixture

Compac

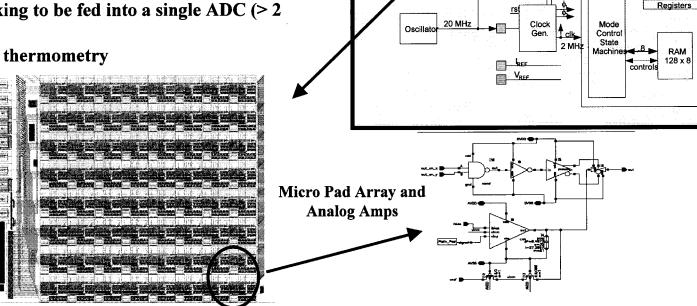
153.6kHz 9.6kHz

Requirements:

- Micro-power and low pin count
- •Direct computer interface with 100% visibility to all working channels
- •Amplifiers with programmable gain and offset using internal look-up table

LabView

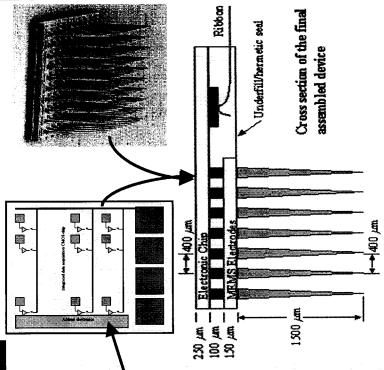
- •Programmable shut down of all unwanted channels
- On-the-fly calibration of amplifier gain and offset parameters
- •Continuous scan of up to 100 analog probe channels @ 20 kHz using time-division multiplexing to be fed into a single ADC (> 2 MHz)
- On chip thermometry



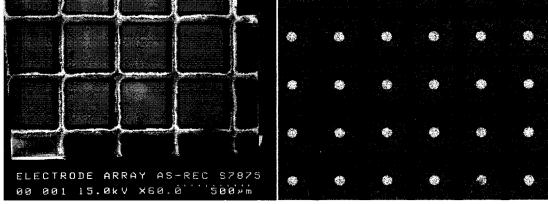


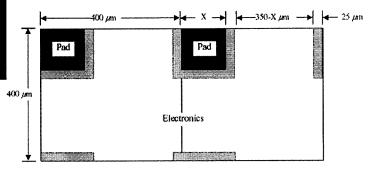
The First Phase, Utilize Electronics to Reduce I/O

- Each electrode terminates to its own pad and needs a wire
- 100 wires are needed for getting signals from all electrodes
- Goal is to heterogeneously integrate electrode array to electronic chip utilizing flip chip technology.
- For heterogeneous integration design a chip with a matrix of micro-pads with exact "foot print" as the pads in the MEMS array.
- To maximize area for electronics, pad size must be minimized.



Data Acquisition Chip with multiplexing circuit reduces the number of wires to 8 and allows 100% "visibility" for all electrodes

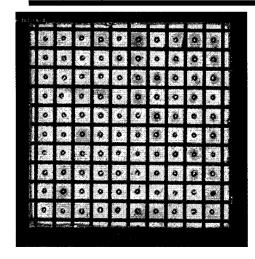


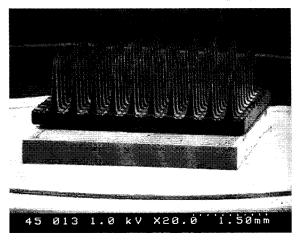


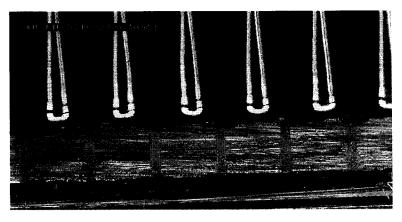


Assembly



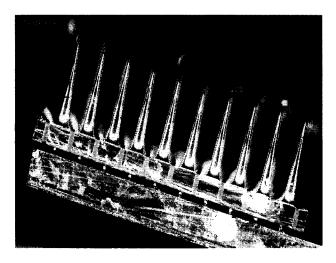


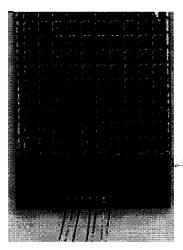


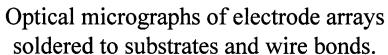


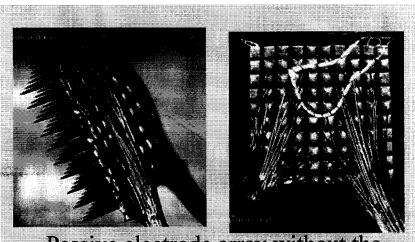
Solder bumped electrode array contact pads.

SEM of electrode array soldered to substrate.









Passive electrode array without the electronics